

**Definition 3.1.10.** A **path** or a **contour** is a curve  $\gamma$  defined on a closed interval  $[a, b]$  which is continuously differentiable or piecewise continuously differentiable. The path  $\gamma$  is **closed** if  $\gamma(a) = \gamma(b)$ .

**Definition 3.1.11.** Given points  $a_0 < a_1 < \cdots < a_m$  and paths  $\gamma_j$  on  $[a_{j-1}, a_j]$ ,  $j = 1, \dots, m$ , such that  $\gamma_j(a_j) = \gamma_{j+1}(a_j)$  for all  $j = 1, \dots, m-1$ , the combined path

$$\Gamma = [\gamma_1, \dots, \gamma_m]$$

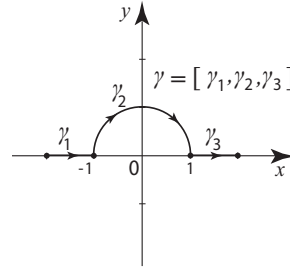
is piecewise defined on  $[a_0, a_m]$  by  $\Gamma(t) = \gamma_j(t)$  for  $t \in [a_{j-1}, a_j]$ ,  $j = 1, \dots, m$ .

Thus, according to Definitions 3.1.10 and 3.1.11, a path or a contour  $\gamma$  is a finite sequence of continuously differentiable curves,  $\gamma_1, \gamma_2, \dots, \gamma_m$ , joined at the endpoints, i.e.,  $\gamma = [\gamma_1, \dots, \gamma_m]$ . The path  $\gamma$  is closed if the initial point of  $\gamma_1$  coincides the terminal point of  $\gamma_m$ , i.e.,  $\gamma_1(a_0) = \gamma_m(a_m)$ .

**Example 3.1.12.** The path  $\gamma = [\gamma_1, \gamma_2, \gamma_3]$  in Figure 3.10 consists of the curves: The line segment  $\gamma_1 = [-2, -1]$ ; the semi-circle  $\gamma_2$ ; and the line segment  $\gamma_3 = [1, 2]$ . We can parametrize  $\gamma$  by the interval  $[-2, 2]$  as follows:

$$\gamma(t) = \begin{cases} t & \text{if } -2 \leq t \leq -1, \\ e^{i\frac{\pi}{2}(1-t)} & \text{if } -1 \leq t \leq 1, \\ t & \text{if } 1 \leq t \leq 2. \end{cases}$$

The choice of the interval  $[-2, 2]$  as the domain of definition was just for convenience. Other closed intervals can be used to parametrize  $\gamma$ .  $\square$

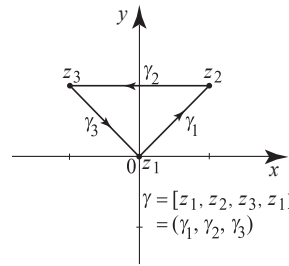


**Fig. 3.10** The path of Example 3.1.12.

**Example 3.1.13. (Polygonal paths)** A **polygonal path**,  $\gamma = [z_1, z_2, \dots, z_n]$  is the union of the line segments  $[z_1, z_2]$ ,  $[z_2, z_3]$ ,  $\dots$ ,  $[z_{n-1}, z_n]$ . This is a piecewise linear path with initial point  $z_1$  and terminal point  $z_n$  and may have self intersections.

A polygonal path is called **simple** if it does not have self intersections, except possibly at the endpoints, that is,  $z_1$  and  $z_n$  may coincide. The polygonal path is called **closed** if  $z_1 = z_n$ .

As an illustration, let  $z_1 = 0$ ,  $z_2 = 1 + i$ , and  $z_3 = -1 + i$ ; then  $\gamma = [z_1, z_2, z_3, z_1]$  is a simple closed polygonal path. To find the equation of  $\gamma$ , we start by finding the equations of the paths  $\gamma_1$ ,  $\gamma_2$ , and  $\gamma_3$ , shown in Figure 3.11. From Example 3.1.2(d), we have



**Fig. 3.11** The closed polygonal path  $[z_1, z_2, z_3, z_1]$